Connectivity Graphs: A Method for Proving Deadlock Freedom Based on Separation Logic

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We got: progress & preservation style proof of deadlock freedom for session types

- Uses separation logic
- Maybe the techniques help toward deadlock free Iris

Session types

Message passing concurrency with first-class channels (Honda [1993])

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GV: functional programming with session types (Gay and Vasconcelos [2010], Wadler [2012])

fork : $(s \rightarrow 1) \rightarrow \overline{s}$ send : $(!t.s) \times t \rightarrow s$ close : End $\rightarrow 1$ receive : $?t.s \rightarrow s \times t$

let $c = \text{fork}(\lambda c'. \dots \text{receive}(c')...)$ in send(c, 23)...

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Initial direct attempt: proofs goals got too complex. Graph reasoning intertwined with language specifics. Encapsulating the graph reasoning made it manageable.

This work: connectivity graphs

- Method for factoring out graph reasoning from reasoning about typing
- Mechanized in the Coq proof assistant
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Threads: { $T_1 \mapsto e_1, ..., T_6 \mapsto e_6$ } Channels: { $C_1 \mapsto buf_1, ..., C_5 \mapsto buf_5$ }

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$$G \vDash
ho$$

wf(ho) := $\exists G.G \vDash
ho$

























Connectivity graph framework:

- Cgraph(V, L) data type for acyclic labeled graphs
- Generic construction for $wf(\rho) := \overline{wf}(P_{\rho})$
 - ▶ Parameterized by local separation logic predicate $P_{\rho}(v)$ for each vertex $v \in G$
- Preservation: graph transformations in separation logic
- Progress: waiting induction principle for Cgraph(V, L)

All generic over vertices V and labels L

 $\frac{\Sigma_1 \vdash e_1 : \tau_1 \qquad \Sigma_2 \vdash e_2 : \tau_2 \qquad \Sigma_1 \cap \Sigma_2 = \emptyset}{\Sigma_1 \cup \Sigma_2 \vdash (e_1, e_2) : \tau_1 \times \tau_2}$

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$$\frac{\Sigma = \{\operatorname{Chan}(a) \mapsto (t, s)\}}{\Sigma \vdash \#a_{t} : s} \qquad \Rightarrow \qquad \frac{\operatorname{own}(\operatorname{Chan}(a) \mapsto (t, s))}{\#a_{t} : s} \ast$$

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Lemmas in separation logic:

$$(\Sigma \vdash K[e] : B) \iff \exists A, \Sigma_1, \Sigma_2. \ (\Sigma_1 \cap \Sigma_2 = \emptyset) \land (\Sigma = \Sigma_1 \cup \Sigma_2) \land (\Sigma_1 \vdash e : A) \land \forall e', \Sigma_3. \ (\Sigma_2 \cap \Sigma_3 = \emptyset) \land (\Sigma_2 \vdash e' : A) \to (\Sigma_2 \cup \Sigma_3 \vdash K[e'] : B)$$

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$$(K[e]:B) \dashv \exists A. (e:A) * \forall e'. (e':A) \rightarrow (K[e']:B)$$

We use the Iris proof mode to reason in separation logic (Krebbers et al. [2017])

Preservation via local graph transformations



Preserves:

- Acyclicity
- Local predicates $P_{\rho}(v)$ used for $\overline{wf}(P_{\rho})$

Preservation via local graph transformations



Progress via waiting induction

Connectivity graph with *waiting dependencies* (►) derived from run-time configuration



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Connectivity graph with *waiting dependencies* (►) derived from run-time configuration



Lemma (Waiting induction)

Let R(v, w) be any relation on the vertices. To prove P(v), we may assume P(w) for all w such that $v \rightarrow w$ and R(v, w), or $w \rightarrow v$ and $\neg R(w, v)$

Mechanization

Mechanization in Coq:

- ► Generic *Cgraph*(*V*, *L*) library: 4999 LOC
- Channels + unrestricted & recursive types language definition: 451 LOC
- ► Language specific deadlock and leak freedom proof: 1688 LOC

 μ GV: linear λ -calculus + fork with single-shot atomic exchange

Global progress & deadlock freedom in Coq (1478 LOC)

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- Global progress & deadlock freedom in Coq (1478 LOC)
- MPGV: linear λ -calculus with multiparty session types
 - Global progress & deadlock freedom in Coq (10400 LOC)

https://github.com/julesjacobs/cgraphs

Benchmark: deadlock freedom for session types using semantic typing with Actris

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 In general, *memory leak freedom* and *deadlock freedom* are equally hard (thanks to POPL reviewers)

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Ideas? Questions?

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Extra slides

Global progress is the standard notion that people use Our POPL reviewers: Can your method prove something stronger?

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Partial deadlock: a set S of threads and channels such that:

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Lemma. All threads and channels are reachable \iff no partial deadlock **Lemma.** Any thread or channel is reachable \implies global progress **Theorem.** For well-typed initial programs, no partial deadlock occurs

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